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Navigation and Ancillary Information Facility - JPL

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The SPICE system has been developed by the Califomia Institute of Technology, under contract with the National Aeronautics and Space Administration



Space Science Data: Two Kinds

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Science Instrument Data including calibration data



SPICE deals with these data

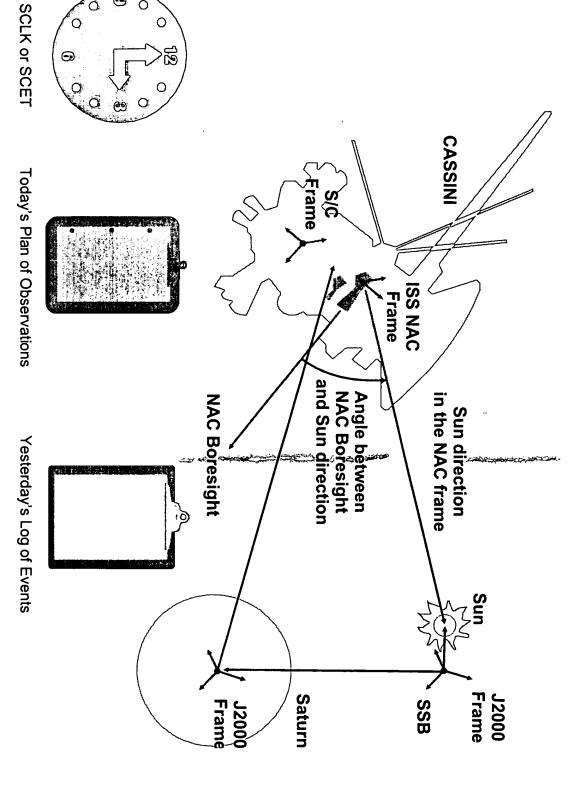
- Some from the spacecraft
- Some from the mission control center
- Some from the spacecraft and instrument builders
- Some from scientists



The Subjects of SPICE

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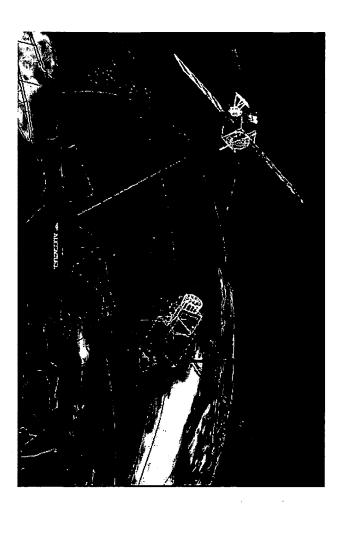
SPICE Deals with Observation Geometry, Time and Events





Why SPICE?

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Knowing observation geometry and events is an important element in the design of space missions and in the analysis of the science data returned from the instruments.

Having standard methods for producing and using ancillary data reduces cost and risk, and can help scientists achieve more meaningful and accurate results.



What are "Ancillary Data"?

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- "Ancillary data" are those that help scientists and engineers determine:
- when and how an instrument was acquiring data
- where the spacecraft was located

how the spacecraft and its instruments were oriented (pointed)

- what was the location, size, shape and orientation of the target being observed
- what other relevant events were occurring on the spacecraft or ground that might affect interpretation of:
- science observations
- spacecraft systems performance



SPICE System Components

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The principal SPICE system components are two

- Data files, often called "kernels" or "kernel files"
- Software, known as the SPICE Toolkit
- This software is, in general, not an executable program

Also part of SPICE are:

- standards
- documentation
- customer support
- system maintenance and continuing development



Genesis of the SPICE Acronym*

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Spacecraft Planet C-matrix (spacecraft attitude) Instrument

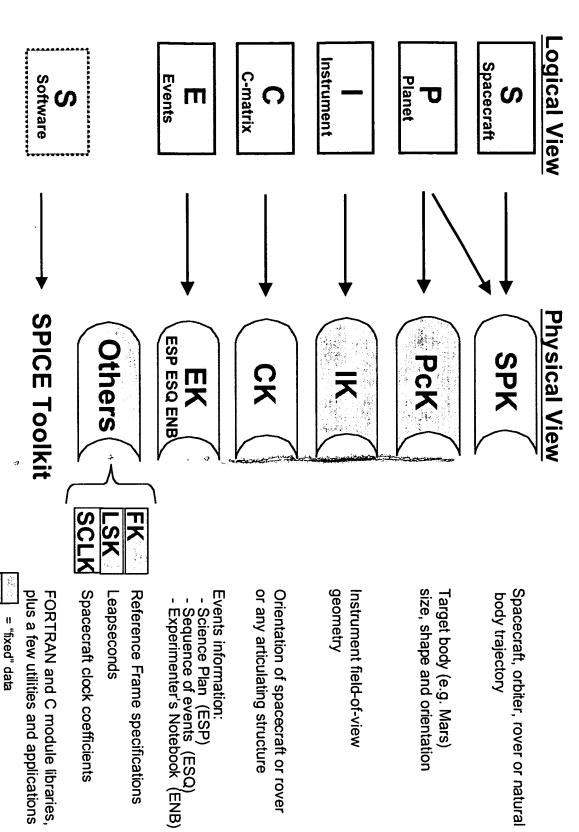
Events

^{*} Coined by Dr. Hugh Kieffer, USGS Astrogeology Branch, Flagstaff AZ



Logical versus Physical View

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= time varying data



SPICE System Contents - '



- Space vehicle ephemeris (trajectory)
- Planet, satellite, comet and asteroid ephemerides
- More generally, position of something relative to something else



- Planet, satellite, comet and asteroid orientations, sizes, shapes
- Possibly other similar "constants" such as parameters for gravitational model, atmospheric model or rings model
- Instrument information such as:
- Field-of-View specifications
- Internal timing



SPICE System Contents - 2



- Instrument platform attitude
- More generally, orientation of something relative to a specified reference frame

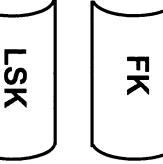


- "Events," broken into three components:
- ESP: Science observation plans
- ESQ: Spacecraft & instrument commands
- ENB: Spacecraft "notebooks" and ground data system logs

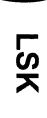


SPICE System Contents - 3

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- Frames Definitions
- Definitions of and specification of frames (coordinate systems) relationships between reference



- Leapseconds Tabulation
- Used for UTC <--> ET time conversions



- Spacecraft Clock Coefficients
- Used for SCLK <--> ET time conversions
- Other Kernels
 - Mission (mappings between names and ID codes)
 - Star (sky) catalog
 - Shape model for small, irregular bodies*
- Terrain*
- Control net

* = under development

UTC = Universal Time Coordinated

ET = Ephemeris Time

SCLK = Spacecraft Clock Time



SPICE System Contents - 4

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SPICE **Toolkit**

FORTRAN C-language

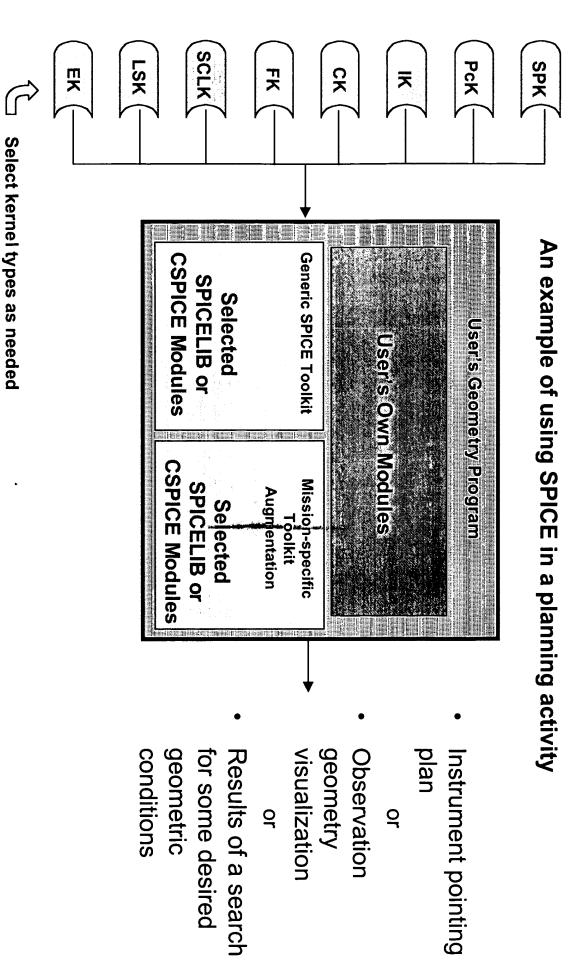
- SPICELIB or CSPICE subroutine library, used to:
- write binary SPICE kernel files
- read all (binary and text) SPICE kernel files

compute quantities derived from SPICE kernel data

- Example ("cookbook") programs
- Utility programs
- Kernel summarization or characterization
- Kernel management
- Application programs (a few)
- e.g. "chronos" time conversion application
- Kernel production programs (a few)
- e.g. "mkspk" trajectory generator
- An IDLSPICE Toolkit is being developed

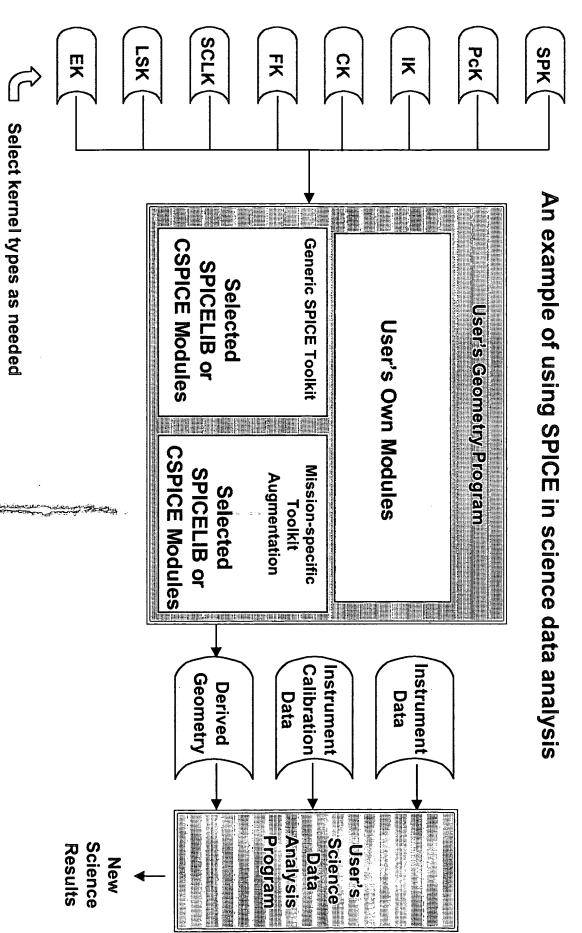


Using SPICE Library Modules





Using SPICE Library Modules





SPICE System Characteristics - 1

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- Portable SPICE kernel files
- Portable SPICE Toolkit software
- PC/Win, PC/Linux, Mac, Sun, SGI, HP, Alpha, VAX

Already ported to and tested on most popular platforms

- Focus is on the customer
- Code is well tested before being released to users
- Once released, code functionality is never changed or removed
- Except NAIF does reserve the right to fix bugs
- Extensive, clear documentation is provided
- Includes well documented source code, provided to each user
- The SPICE Toolkit contains some example ("cookbook") programs
- An extensive set of SPICE tutorials is available



SPICE System Characteristics - 2

- All computations are double precision
- System includes built-in exception handling
- Trace back, configurable action upon detection of an exception
- and natural bodies (planets, satellites, comets, asteroids) Has access to all of JPL's latest integrated ephemerides for spacecraft
- Kernel files are separable
- Use only those you need for a particular application
- Kernel files are extensible
- New data "types" can be added within a family
- New kinds of kernels can be defined
- Broad applicability and good value
- Multimission and multidiscipline (see list of major projects)
- SPICE development and maintenance costs are shared across many customers



SPICE System Characteristics - 3

- The generic SPICE Toolkit is generally free to individual users
- Core SPICE system development is funded by NASA's Office of Space
- of NASA missions, and for some cooperative missions NASA flight projects fund NAIF to adapt and deploy SPICE in support
- E.g. Clementine, Huygens Probe, Mars Express, ... possibly Rosetta
- SPK files to schedule Deep Space Network stations NASA provides consultation and some tools for agencies using SPICE
- SPICE files Very few restrictions on distribution and use of SPICE software and
- Note: SPICE software is copyrighted © by the California Institute of lechnology



For What Jobs is SPICE Used?

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Increasing mission maturity (time)

- Mission planning, modeling and visualization
- Pre-flight mission evaluation from a science perspective
- Detailed science observation planning
- Mission operations engineering functions
- Science data analysis, including correlation of results between instruments, and with data obtained from other missions
- Data archiving, for future use by others



Education and Public outreach



Www What Vehicle Types Can Be Supported?

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Cruise/Flyby

- Remote sensing
- In-situ measurement
- Instrument calibration

Landers

- Remote sensing
- In-situ measurements
- Surface analysis
- Rover or balloon relay

Orbiters

- Remote sensing
- In-situ measurement
- Communications relay

Rovers

- Remote sensing
- In-situ sensing
- Local terrain characterization

Balloons*

- Remotė̇ sensing
- In-situ measurements



Major SPICE Customers

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American Company of the Company of t	Mars Recon. Orbiter		
To the control of the	CONTOUR	. 2	
A PARTY OF THE CASE OF THE CAS	Deep Impact		
	DSN Metric Predicts [S]	Space VLBI [P]	
The same and the same and the same and the same same and the same and	Mars Express (ESA)	Mars Polar Lander	The same of the sa
and were stated over the transplacement of the control of the cont	Genesis	Mars Climate Orbiter	· · · · · · · · · · · · · · · · · · ·
Space Interferometry	SIRTF [S]	Mars Pathfinder	Voyagers [P]
Pluto	Mars Exploration Rover	OTD (by MSFC)	Ulysses [P]
Europa Orbiter	Mars Odyssey	MSTI-3 (by ACT Corp.)	Phobos 2 [P] (Russia)
BepiColombo (ESA)	Deep Space 1	ISO [S]	Haley armada [P]
Rosetta (ESA)	Cassini/Huygens	Hubble Telescope [S]	Pioner 10/11 [P]
Starlight	Stardust	Mars 96 (Russia)	Viking Orbiters [P]
Messenger	Mars Global Surveyor	Mars Observer	Mariner 10 [P]
Nozomi (Japan)	NEAR	Clementine (NRL)	Mariner 9 [P]
Mars 07, 09,	Galileo	Magellan [P]	Apollo 15, 16 [P]
Future Possibilities	Current Customers	Past Customers	Restorations

[P] = partial use of SPICE

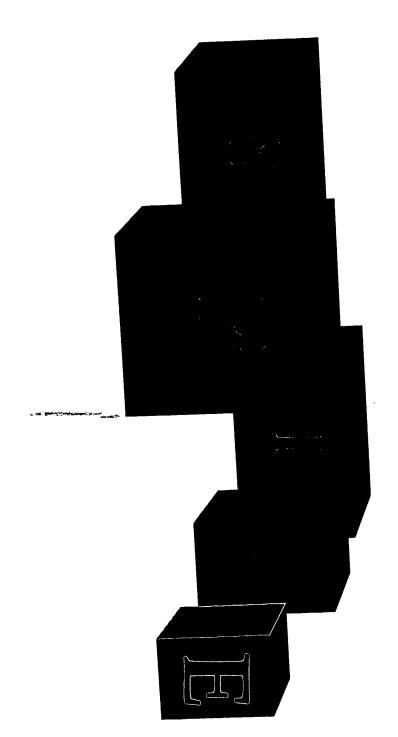
[S] = special tools or services provided by NAIF



Building Blocks for Your Applications

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a model and core set of blocks for building tools that can exploration program help execute a multimission, international space NASA offers its "SPICE" ancillary information system as





What Can You Do With SPICE? Examples - 1

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Mission Design

- Compute all interesting orbit properties; compare these with those of another design, or with another mission
- Evaluate possibilities for relay link times and duration

Science

- Compute footprint coverage over time; compare against those from another instrument on your spacecraft or on a different spacecraft
- Design specific observations to be acquired
- Compute observation geometry needed to analyze your data, such as:
- Lighting angles
- Location (LAT/LON) of instrument footprint
- Range and local time



What Can You Do With SPICE? Examples - 2

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Mission Operations

- Predict or evaluate telecommunications link performance
- Analyze spacecraft orientation history

Determine elevation and rise/set times of sun and tracking stations

Compute location of a long range rover or a balloon

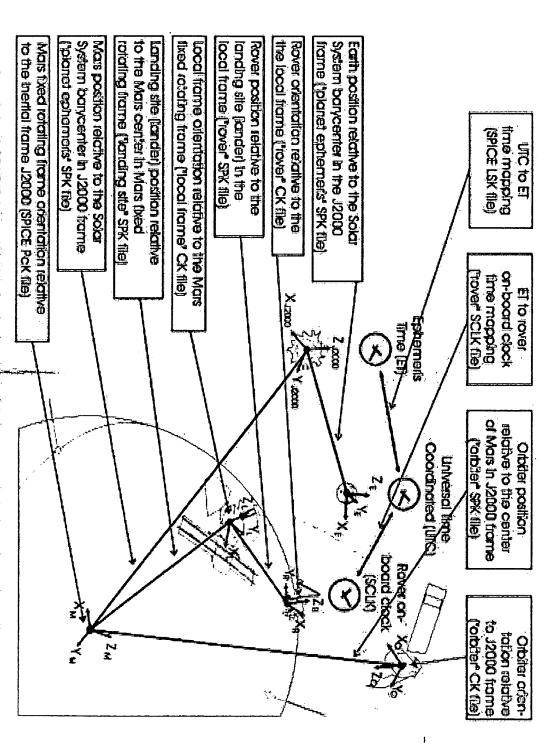
Visualization, Education and Public Outreach

- Provide geometry used to drive web pages giving interesting parameters such as ranges, velocities, time of day on Mars
- Provide geometry for animations showing orbiter location and orientation, instrument footprint projected on the surface, and locations of surface assets or natural features of interest
- Help get upper class students involved in space mission design



Global SPICE Geometry

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Applying SPICE to a Full Planetary Investigation: Orbiter, Lander, Rover



Orbiter Geometry

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spacecraft frame; determined from the Solar Array gimbal location with respect to the apacearoff frame center in the spacecraft mechanical drawings;

with respect to the spacecraft frame Mars Orbiter Camera ofentation stored in the structures SPK file

determined during colloidions;

determined during calibrations, stored with respect to the spaceardt frame. Mais Orbitar Laser Allimiter orientation in the attimiter IK and the spaceach spocecial frame Definitions files dated in the camera K and the Frame Definitions files

> with respect to the spacecraft frame. computed from gimbal anglessent Solar Array gimbal frame orientation down in the spocecial telement; stored in a Salar Array CK fie

balar array gimbal trame; determined Magnetameter Sensor location relative from mechanical drawings; stored in to the solar array gimbal in the mie or chuckines SPK file

determined from mechanical drawings: stored in the incrnetometer to and the with respect to the solar array frame: Magnetometer Sensor offentation spacecraft frame Definitions files

with respect to the spaceciast stame telemetry; stored in a Antenna CK file down in the spacecraft engineering computed from grabal angles sent **HGA** gimbal frame orientation

HGA Phase center location relative to frame; determined from spacecraft the HGA gimbal in the HGA gimbal mechanical drawings; stored in the Sic adjuctures SPK file

computed on-board and sent down in

respect to the J2000 inertial frame;

Spacecraft Frame orientation with

the apacecraft engineering telemetry:

stored in a Spacecraft CK file

from mechanical drawings; stored in RGA gimbal location with respect to the spacecraft frame; determined the spacecial frame center in the the crc shuchures SPK fle

the J2000 Inertial frame; computed as the result of orbit determination;

stored in a spacecraft SPK file

Spacecraft padition and velocity relative to the center of Marsin

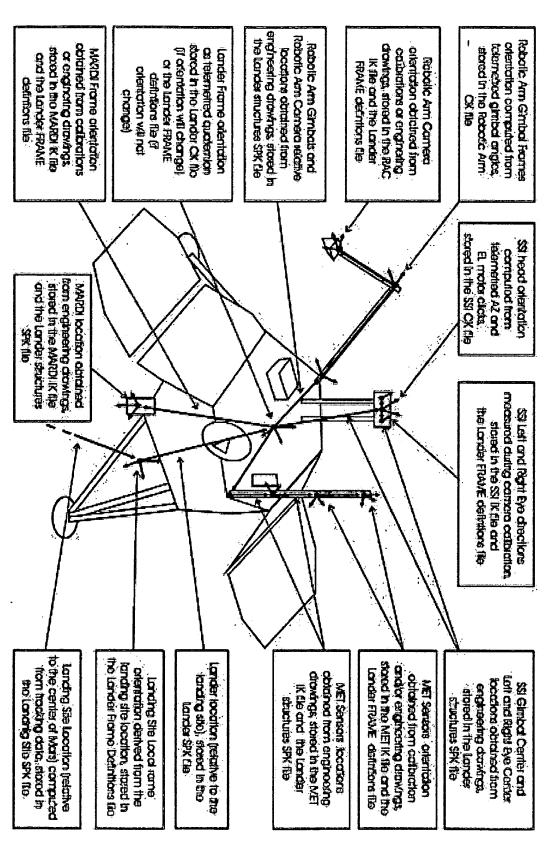
from spacecraft mechanical drawings: to the HGA gimbal frame; determined HGA frame orientation with respect stored in the spacecraft Frame

Applying SPICE to an Orbiter (MGS)



_ander Geometry

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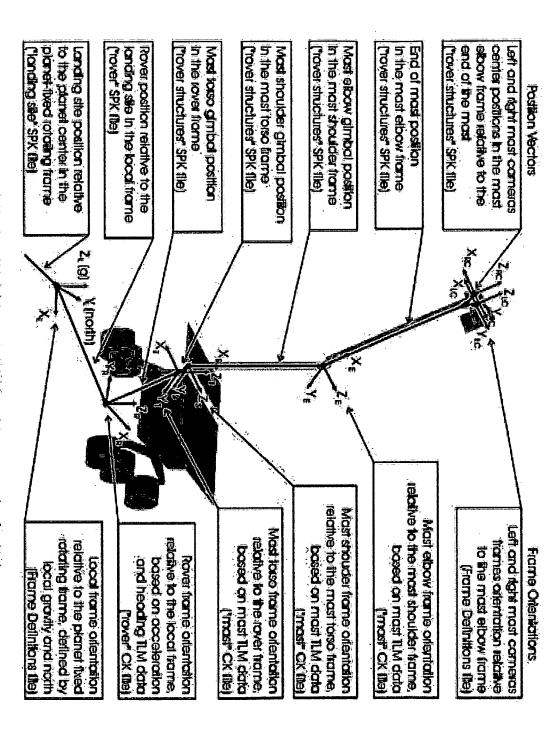


Applying SPICE to a Lander (M98)



Rover Geometry

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Applying SPICE to a Sujface Rover (Rocky-7)



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A Few Examples of SPICE-Based Applications



Convey Trajectory Design

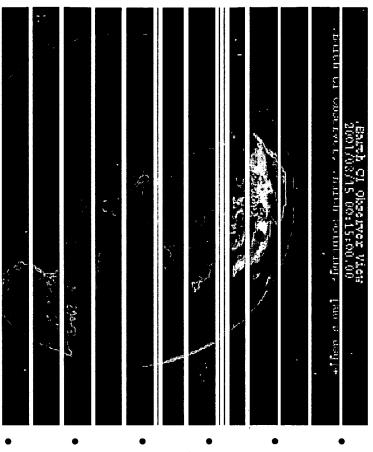
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in other analysis and visualization tools in the overall ephemerides in the SPICE SPK format, for easy use Trajectory design tools can produce output mission design process



Visualization Tools

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- Satellite Tool Kit (STK) ®
- Analytical Graphics Inc. (Uses only SPK files)
- Satellite Orbit Analysis Program (SOAP) ®
- Aerospace Corporation
- Pointing Design Tool (PDT)
- JPL
- Science Opportunity Analyzer (SOA)
- JPL
- Mars Express Science SOA (MEXSOA)
- DLR, Inst. for Planetary Exploration
- Micro-Helm
- JPL
- Cassini Pointing Designer (CASPER)
- Univ. of Colorado
- Interactive Data Language (IDL) ®
- Research Systems Inc.

(Using SPICE "wrappers" around CSPICE modules)



Data Processing Tools

- systems which obtain needed observation geometry Numerous science teams have developed their own using SPICE files and allied SPICE Toolkit modules observation planning and data processing software
- Engineering teams have built analysis tools which files and allied SPICE Toolkit modules obtain needed observation geometry using SPICE
- Examples: telecommunications and thermal analysis



A Simple, Limited Geometry Calculator **GEOCALC**

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	37.317459 37.317454 0.000007	_ u u	(deg) (deg) (deg)	Phase angle Solar incidence angle Emission angle	Phase Solar Emiss
	114.786907 -14.773171	(deg) 116 (deg) -16	longitude latitude	Surface planetocentric Surface planetocentric	Surfa Surfa
	707724	Jan 4 08:52:00.707724	Mars MEX NONE 2004	Target Observer Aberration correction Time	Target Observer Aberrati Time
t	on observer	int, as seen from observer	surface po	Illumination angles at surface point,	Illum
F7	Planetodetic	[c	R+17-8	¢ ¢	
	Planetocentric	>	NOW.	» >	
	Coordinate System		Aberration Correction	Abernat	
	2004 Jan 4 08:52:00.707724	200	3	Observation epoch	
Compose	-14.773171	-14	ati tude	Surface point latitude	
	114.786907	12	ong'i tude	Surface point longitude	
		ME X		Observer	
	,så.	Mars		Target	· · · · · ·

		:	Angles	Illumination L	Ill
		9	Drawings Log	Computations	Kernels
		**************************************		Java/Spice Interface test	/e∧er □

Compute the phase, solar incidence and emission angles at some surface point on a target as seen from an observer at some epoch.

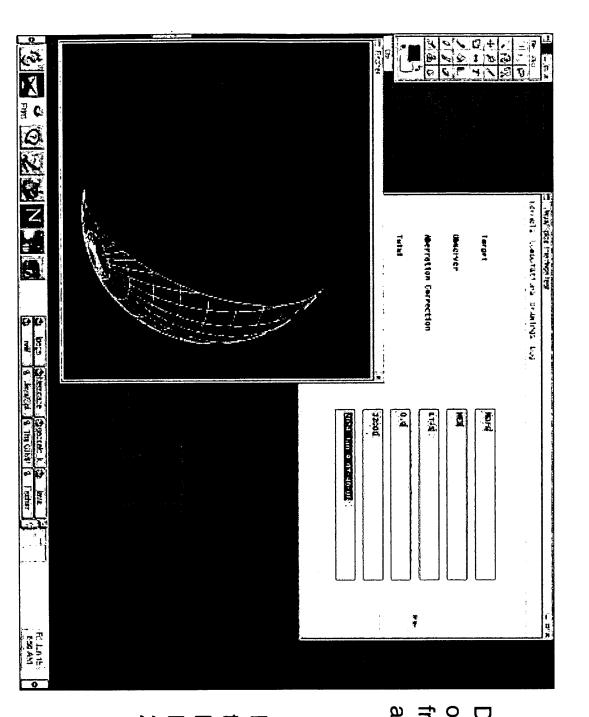
In this example, compute the illumination angles on Mars at LON 114.7 and LAT -14.7 as seen from Mars Express on 2004 JAN 4 08:52:00. Can pick either planetocentric or planetodetic frame.



GEOCALC

Primitive Geometry "Snapshot" Mode

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Draw the appearance of a target as seen from an observer at some epoch.

In this example, draw the appearance of Mars as seen from Mars Express on 2004 JAN 4 07:40:00.



Supported Platforms - 1

- of popular platforms The SPICE Toolkit has been ported to a wide variety
- Each platform is characterized by
- Hardware type
- **Operating System**
- Compiler
- Selected compilation options
- each supported platform NAIF provides separate SPICE Toolkit packages for



Supported Platforms - 2 Navigation and Ancillary Information Facility - JPL

	Absoft Fortran 4.4	MAC-OS	MAC Power PC
Metrowerks CodeWarrior C 5.3	Language Systems Fortran 3.3	MAC-OS	MAC Power PC
HP C	HP Fortran	HP-UX	HP
N/A	Digital Fortran	SMA	DEC VAX
N/A	Digital Fortran, GFLOAT	Open VMS	DEC Alpha
N/A	Digital Fortran, DFLOAT	Open VMS	DEC Alpha
Digital C	Digital Fortran	Alpha Digital Unix	DEC Alpha
C Compiler / Options	Fortran Compiler / Options	Operating System	Hardware



Supported Platforms - 3 Navigation and Ancillary Information Facility - JPL

MS Visual C++/C	Digital Fortran	MS Windows	PC
MS Visual C++/C	Digital Fortran,	MS Windows	PC
((
gcc	g77	Red Hat Linux 6.1+	PC
	,		
gcc	Fort77 (f2c/gcc)	Red Hat Linux	PC
	Operation		
c compiler / Options	Options		
C Compiler / Options	Entran Compiler /	Operating System	Hardware



Access to Toolkit and Tutorials

- available from NAIF's anomymous ftp server: Packages for all SPICE Toolkit environments are
- ftp://naif.jpl.nasa.gov/pub/naif/toolkit/
- Select either the FORTRAN or C directory
- Select the environment you want (platform/OS/compiler)
- Follow the instructions in the README file
- A set of SPICE tutorial packages is available from NAIF's anonymous ftp server:
- ftp://naif.jpl.nasa.gov/pub/naif/tutorial/current/
- These are available in MS Office format (and soon PDF also)
- The file named 02_tutorials_index provides an index of the complete set of packages (see next two charts)
- Download the tutorials using binary mode of FTP



SPICE Tutorials - 1

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Tutorial	File Name	Length	Торіс
) Pages	
	reduite		Description of mese intollars
2	tutorials_index.xls	1	Index of SPICE Tutorials
ယ	purpose_scope	ω	Tutorials Purpose and Scope
4	tutorials_intro	6	Tutorials Introduction
	motivation	6	Motivation for Development of SPICE
6	spice_overview	18	SPICE Overview
7	concepts	47	Basic Concepts (of observation geometry, regardless of SPICE)
8	intro_to_kernels	11	Intro to Kernel Files
9	porting_kernels	1	Porting Kernels Between Computers
10	intro_to_toolkit	23	Intro to Toolkit: libraries, utilities, applications, documentation
1	metadata	8	Metadata in SPICE Kernels (use of comment area, etc.)
12	conventions	12	SPICE Conventions
13	time	10	Time: Conversions and Formats
14	spk	26	SPK (Ephemeris subsystem)
15	pck	15	PCK (Planetary cartographic constants)
16	i,	22	IK (Instrument information)
17	ck	16	CK (Orientation information)
18	**************************************	8	FK (Reference frames specifications)



SPICE Tutorials - 2

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Tutoria	File Name	Length	
Number		(pages)	
21	3K	4	MK: The Mission Kernel Concept
22	derived_quantities	15	Computing Derived Quantities
23	other_functions	19	Other Useful SPICELIB Functions
24	toolkit_utils	24	Using SPICE Toolkit Utilities
25	toolkit_apps	29	Using Toolkit Applications
26	idl_interface	8	Interfacing IDE to CSPICE
27	program_c	23	Demo: writing a SPICE-based application (C language)
28	program_fortran	28	Demo: writing a SPICE-based application (Fortran)
29	program_visibility	12	Demo: computing visibility (Fortran)
30	spice_dev_plans	16	Plans for Further SPICE System Development
31	installing	6	SPICE Toolkit Installation
32	exceptions	18	Exception Handling (How SPICE handles detectable errors)
33	common_problems	5	Common Problems (a "pointer" to Common Problems document)
34	ek_intro	9	Events Kernel (EK): Introduction
35	ek_esp	္မယ	EK - Science Plan Component (ESP)
36	ek_esq	14	EK - Sequence Component (ESQ)
37	ek_enb	13	EK - Notebook Component (ENB)
သ 8	docs_taxonomy	10	SPICE Documentation Taxonomy
	most_useful	*	Summary of the most useful SPICELIB subroutines (MS Word)

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